

Answers exam FYTB13, May 31, 2017

1. a) Gauss law: $\nabla \cdot \vec{D} = \rho_f \Rightarrow \oint \vec{D} \cdot d\vec{S} = Q_{f, \text{enc}}$
Spherical symmetry $\Rightarrow \vec{D} = \frac{Q}{4\pi r^2} \hat{r}$ for all r

b) $\vec{D} = \epsilon_0 \epsilon_r \vec{E} \Rightarrow$

$$\vec{E}_{r < a} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r}$$
$$\vec{E}_{a < r < b} = \frac{Q}{4\pi \epsilon_0 \epsilon_r r^2} \hat{r}, \quad \epsilon_r = 2$$
$$\vec{E}_{r > b} = \frac{Q}{4\pi \epsilon_0 r^2} \hat{r}$$

c) $\nabla \cdot \vec{E} = \frac{\rho}{\epsilon_0} \Rightarrow \oint \vec{E} \cdot d\vec{S} = \frac{Q_{\text{enc}}}{\epsilon_0}$

Gaussian pillbox $\Rightarrow (\vec{E}_{\text{above}} - \vec{E}_{\text{below}}) \cdot \hat{r} dA = \frac{\sigma}{\epsilon_0} dA$

$$\Rightarrow \sigma_{r=b} = \frac{Q}{4\pi b^2} \left(1 - \frac{1}{\epsilon_r}\right) = \frac{1}{2} \frac{Q}{4\pi b^2}$$

$$\sigma_{r=a} = \frac{Q}{4\pi a^2} \left(\frac{1}{\epsilon_r} - 1\right) = -\frac{1}{2} \frac{Q}{4\pi a^2}$$

Integration $\Rightarrow \oint \sigma_{r=b} dS = \frac{Q}{2}$

$$\oint \sigma_{r=a} dS = -\frac{Q}{2}$$

d) By definition $\vec{E} = -\nabla V$ (static field)

Spherical coord + symmetry $\Rightarrow \vec{E} = -\hat{r} \frac{\partial}{\partial r} V$

$$\Rightarrow V_{r > b} = -\int_b^r \frac{Q}{4\pi \epsilon_0 r'^2} dr' = \frac{Q}{4\pi \epsilon_0 r}$$

$$V_{a < r < b} = \frac{Q}{4\pi \epsilon_0 b} - \int_b^r \frac{Q}{4\pi \epsilon_0 \epsilon_r r'^2} dr' = \frac{Q}{4\pi \epsilon_0} \left(\frac{1}{b} + \frac{1}{r \epsilon_r} - \frac{1}{b \epsilon_r} \right)$$

$$\begin{aligned}
 V_{\text{nea}} &= \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{b} + \frac{1}{\epsilon_r} \left(\frac{1}{a} - \frac{1}{b} \right) \right) - \int_a^r \frac{Q}{4\pi\epsilon_0 r'^2} dr' = \\
 &= \frac{Q}{4\pi\epsilon_0} \left(\frac{1}{b} + \frac{1}{\epsilon_r} \left(\frac{1}{a} - \frac{1}{b} \right) - \frac{1}{a} + \frac{1}{r} \right) = \\
 &= \frac{Q}{4\pi\epsilon_0} \left(\left(\frac{1}{a} - \frac{1}{b} \right) \left(\frac{1}{\epsilon_r} - 1 \right) + \frac{1}{r} \right)
 \end{aligned}$$

$$e) \quad W = \frac{1}{2} \int \vec{E} \cdot \vec{D} d^3r$$

$$\begin{aligned}
 \Rightarrow \Delta W &= W_{\text{with}} - W_{\text{without}} = \frac{1}{2} \int (\vec{E}_{\text{with}} - \vec{E}_{\text{without}}) \cdot \vec{D} d^3r = \\
 &= \frac{1}{2} \frac{Q^2}{(4\pi)^2 \epsilon_0} \int_a^b \left(\frac{1}{r^2} \right)^2 \left(\frac{1}{\epsilon_r} - 1 \right) r^2 dr \int d\Omega = \\
 &= \frac{Q^2}{8\pi\epsilon_0} \left(\frac{1}{\epsilon_r} - 1 \right) \left[-\frac{1}{r} \right]_a^b = \frac{Q^2}{8\pi\epsilon_0} \underbrace{\left(\frac{1}{\epsilon_r} - 1 \right)}_{<0} \underbrace{\left(\frac{1}{a} - \frac{1}{b} \right)}_{>0}
 \end{aligned}$$

$$\therefore \Delta W < 0$$

f) ΔW negative means the configuration with the dielectric is energetically more favourable

2. a) magnetic flux $\Phi = \int \vec{B} \cdot d\vec{S} = [\vec{B} = \vec{\nabla} \times \vec{A}] =$
 $= \int (\vec{\nabla} \times \vec{A}) \cdot d\vec{S} = [\text{Stokes}] = \oint_C \vec{A} \cdot d\vec{l}$

b) $\vec{A}_1(\vec{r}_2) = \frac{\mu_0 I_1}{4\pi} \oint_{C_1} \frac{d\vec{l}_1}{|\vec{r}_2 - \vec{r}_1|}$

$\Rightarrow \Phi_{I_2} = \oint_{C_2} \vec{A}_1(\vec{r}_2) \cdot d\vec{l}_2 = I_1 \frac{\mu_0}{4\pi} \underbrace{\oint_{C_2} \oint_{C_1} \frac{d\vec{l}_1}{|\vec{r}_2 - \vec{r}_1|} \cdot d\vec{l}_2}_{M_{21}}$

c) $M_{12} = \frac{\mu_0}{4\pi} \oint_{C_1} \oint_{C_2} \frac{d\vec{l}_2}{|\vec{r}_1 - \vec{r}_2|} \cdot d\vec{l}_1 = [\text{change ord of int.}] =$
 $= \frac{\mu_0}{4\pi} \oint_{C_2} \oint_{C_1} \frac{d\vec{l}_1}{|\vec{r}_1 - \vec{r}_2|} \cdot d\vec{l}_2 = [|\vec{r}_1 - \vec{r}_2| = |\vec{r}_2 - \vec{r}_1|] = M_{21}$

$$3a) \quad \vec{M} = M \hat{z} \quad \text{for } r < b$$

$$ME \quad \begin{cases} \vec{\nabla} \cdot \vec{B} = 0 & [\vec{H} = \frac{1}{\mu_0} \vec{B} - \vec{M}] \Rightarrow \vec{\nabla} \cdot \vec{H} = -\vec{\nabla} \cdot \vec{M} \\ \vec{\nabla} \times \vec{H} = \vec{J}_f + \frac{\partial}{\partial t} \vec{D} & [\vec{J}_f = 0, \frac{\partial}{\partial t} \vec{D} = 0] \Rightarrow \vec{\nabla} \times \vec{H} = 0 \end{cases}$$

$$\Rightarrow \vec{H} = -\vec{\nabla} \psi, \quad \nabla^2 \psi = \vec{\nabla} \cdot \vec{M}$$

$$b) \quad \vec{\nabla} \cdot \vec{B} = 0 \Rightarrow \int \vec{\nabla} \cdot \vec{B} d^3r = 0$$

$$\text{Gaussian pillbox} \Rightarrow \hat{r} \cdot (\vec{B}_{out} - \vec{B}_{in}) = 0$$

$$\Rightarrow \hat{r} \cdot (\vec{H}_{out} - \vec{H}_{in}) = -\hat{r} \cdot (\vec{M}_{out} - \vec{M}_{in}) = M \cos \theta$$

$= 0 \quad = M \hat{z}, \quad \hat{z} = \hat{r} \cos \theta - \hat{\theta} \sin \theta$

$$c) \quad \vec{M} = \text{const} \Rightarrow \vec{\nabla} \cdot \vec{M} = 0 \Rightarrow \nabla^2 \psi = 0$$

Symmetry \Rightarrow general sol'n

$$\psi = \sum_l (A_l r^l + B_l \frac{1}{r^{l+1}}) P_l(\cos \theta)$$

$$r > b: \psi \rightarrow 0 \text{ as } r \rightarrow \infty \Rightarrow A_l = 0 \text{ for all } l$$

$$r < b: \psi \text{ finite as } r \rightarrow 0 \Rightarrow B_l = 0 \quad \text{--- } l \text{---}$$

$r = b: \psi$ continuous

$$\sum_l A_l^{\text{in}} b^l P_l(\cos \theta) = \sum_l B_l^{\text{out}} \frac{1}{b^{l+1}} P_l(\cos \theta)$$

$$P_l \text{ orthonormal} \Rightarrow A_l^{\text{in}} b^l = B_l^{\text{out}} \frac{1}{b^{l+1}}$$

$r = b: \hat{r} \cdot \vec{H}$ discontinuous

$$-\frac{\partial}{\partial r} \psi_{r>b} + \frac{\partial}{\partial r} \psi_{r<b} = M \cos \theta$$

$$\Rightarrow \sum_l (l+1) \frac{B_l^{\text{out}}}{b^{l+2}} P_l(\cos\theta) + \sum_l l \frac{B_l^{\text{out}}}{b^{2l+1}} b^{l-1} P_l(\cos\theta) = M \cos\theta$$

$$P_l \text{ orthonormal} \Rightarrow B_l^{\text{out}} = 0 \text{ for } l \neq 1$$

$$B_1^{\text{out}} \left(\frac{2}{b^3} + \frac{1}{b^3} \right) = M \Rightarrow B_1^{\text{out}} = \frac{M b^3}{3}$$

$$\Rightarrow A_1^{\text{out}} = \frac{M}{3}$$

$$\therefore \psi_{r>b} = \frac{M b^3}{3 r^2} \cos\theta, \quad \psi_{r<b} = \frac{M}{3} r \cos\theta$$

$$d) \vec{H} = -\vec{\nabla} \psi \Rightarrow \begin{cases} \vec{H}_{r>b} = \frac{M b^3}{3 r^3} (2 \cos\theta \hat{r} + \sin\theta \hat{\theta}) \\ \vec{H}_{r<b} = -\frac{1}{3} M (\hat{r} \cos\theta - \hat{\theta} \sin\theta) = -\frac{\vec{M}}{3} \end{cases}$$

$$\vec{B} = \mu_0 (\vec{H} + \vec{M}) \Rightarrow$$

$$\begin{cases} \vec{B}_{r>b} = \mu_0 \frac{M b^3}{3 r^3} (2 \cos\theta \hat{r} + \sin\theta \hat{\theta}) \\ \vec{B}_{r<b} = \mu_0 \frac{2}{3} \vec{M} \end{cases}$$

$$4a) \vec{A} = (\tilde{a}_x \hat{x} + \tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}$$

$$\vec{V} = c \tilde{a}_x e^{i(kx - \omega t)}$$

$$\text{Lorenz gauge: } \frac{1}{c^2} \frac{\partial}{\partial t} \vec{V} + \vec{\nabla} \cdot \vec{A} = 0$$

$$\frac{1}{c^2} \frac{\partial}{\partial t} \vec{V} = \frac{1}{c^2} (-i\omega) c \tilde{a}_x e^{i(kx - \omega t)}$$

$$\vec{\nabla} \cdot \vec{A} = ik \tilde{a}_x e^{i(kx - \omega t)}$$

$$\Rightarrow \frac{1}{c^2} \frac{\partial}{\partial t} \vec{V} + \vec{\nabla} \cdot \vec{A} = \left(-i\frac{\omega}{c} + ik\right) \tilde{a}_x e^{i(kx - \omega t)} = 0$$

$$\frac{\omega}{c} = k$$

$$b) \vec{E} = -\vec{\nabla} \vec{V} - \frac{\partial}{\partial t} \vec{A} =$$

$$= -c \tilde{a}_x ik \hat{x} e^{i(kx - \omega t)} + i\omega (\tilde{a}_x \hat{x} + \tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}$$

$$= [kc = \omega] = i\omega (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}$$

$$\vec{B} = \vec{\nabla} \times \vec{A} = i \vec{k} \times \vec{A} =$$

$$= \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ k & 0 & 0 \\ \tilde{a}_x & \tilde{a}_y & \tilde{a}_z \end{vmatrix} e^{i(kx - \omega t)} = ik(-\tilde{a}_z \hat{y} + \tilde{a}_y \hat{z}) e^{i(kx - \omega t)}$$

$$\vec{k} = k \hat{x}, \quad \vec{B}, \vec{E} \perp \hat{x} \Rightarrow \vec{B} \cdot \vec{k} = \vec{E} \cdot \vec{k} = 0$$

$$\vec{E} \cdot \vec{B} \propto (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) \cdot (-\tilde{a}_z \hat{y} + \tilde{a}_y \hat{z}) = -\tilde{a}_y \tilde{a}_z + \tilde{a}_y \tilde{a}_z = 0$$

c) homogeneous wave-equ

$$\left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right) \vec{E} = 0, \quad \left(\frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \nabla^2\right) \vec{B} = 0$$

$$\frac{1}{c^2} \frac{\partial^2}{\partial t^2} \vec{E} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} (i\omega (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}) =$$

$$= \frac{(-i\omega)^2}{c^2} (i\omega (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}) = -\frac{\omega^2}{c^2} \vec{E}$$

$$\nabla^2 \vec{E} = \nabla^2 (i\omega (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}) =$$

$$= (ik)^2 (i\omega (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) e^{i(kx - \omega t)}) = -k^2 \vec{E}$$

$$= \left[k = \frac{\omega}{c}\right] = -\frac{\omega^2}{c^2} \vec{E} = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} \vec{E} \quad \square$$

same way for \vec{B}

d) By def. $\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$

Complex not. $\langle \vec{S} \rangle = \frac{1}{2\mu_0} \vec{E} \times \vec{B}^* =$

$$= \frac{1}{2\mu_0} -i^2 \omega k \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ \tilde{a}_y & \tilde{a}_z & -\tilde{a}_y^* \\ -\tilde{a}_z^* & \tilde{a}_y & \tilde{a}_z \end{vmatrix} = \frac{1}{2\mu_0} \omega k \hat{x} (|\tilde{a}_y|^2 + |\tilde{a}_z|^2)$$

e) Lorentz force: $\vec{F} = q(\vec{E} + \vec{v} \times \vec{B})$

$$\vec{v} \times \vec{B} = \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ v & 0 & 0 \\ 0 & -\tilde{a}_z & \tilde{a}_y \end{vmatrix} = -v(\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z})$$

$$\Rightarrow \vec{F} = q \operatorname{Re} \left[\underbrace{(i\omega (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}) - i\omega k (\tilde{a}_y \hat{y} + \tilde{a}_z \hat{z}))}_{= 0 \text{ if } v = c} e^{i(kx - \omega t)} \right]$$

$$= 0 \text{ if } v = c$$